

## Collision Avoidance Controller

Service Manual



## WASHLINK COLLISION AVOIDANCE CONTROLLER SERVICE MANUAL

This document provides comprehensive operational procedures for the Washlink Collision Avoidance Controller. In this manual, we will discuss the Setup and Operation of the Collision Avoidance Controller.

If further assistance is needed, please contact the Distributor from which the product was purchased.

When calling for assistance, you must have the following information available:					
UL Number:					
Distributor Name:					
Installation Date:					

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# Chapter

#### 1 Features

Features of Washlink Systems Collision Avoidance Controller;

The ability to use input device of choice, eyes, loop, wands etc.

Industry proven components from Siemens Worldwide

Built in car counter for added security

External reset button

Warning isolation relay for any external device, horn, light etc.

Equipment auto re-start on isolation relay for use with any voltage

Equipment auto stop on isolation relay for use with any voltage

Go/Exit light control

Cycle counter for maintenance purposes

Corrosion proof non-metallic enclosure

Works on ALL brands of car wash equipment

Works on ALL brands of car wash equipment controllers

UL Listed and CE compliant







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#### 2 Installation

The Washlink Collision Avoidance Controller should be mounted securely to a stable and permanent wall. Choose a location in the equipment room that is easily accessible and provides protection from the elements.

#### 2.1 Power Requirements

The Collision Avoidance Controller requires 110-230vac Branch Circuit protection (provided by Customer).

This circuit should be connected to Fuse 101 PLC.



**Warning:** All electrical work should be performed by a qualified and licensed electrician.

All electrical work should meet or exceed National and Local codes and ordinances.



Warning: Risk of electrical shock.

More than one disconnect my be required to be de-energized before servicing equipment.



Warning: Bonding between conduit connection is not automatic and must be provided as

part of the installation.

#### **2.1.1 Inputs**

The Collision Avoidance Controller Input power is supplied by the PLC. All PLC Inputs are 24vdc should be wired as a Normally Open Circuit.



Warning: All Inputs are 24vdc.

Any other voltage will damage the Controller and void warranty.

The **Conveyor Input** is required for the Collision Avoidance Controller to work. This allows the Collision Avoidance Controller to only operate while the conveyor is on.



Note:

An interface relay may be needed if the existing **Conveyor Switch** does not have an extra Normally Open contact.

The **Sensor #1 Input** is required for the Collision Avoidance Controller to work. The **Sensor #2 Input** is required for the Collision Avoidance Controller to work.

For the system to fire the **STOP** relay the following must occur in this order:

- 1) Conveyor Input must be high
- 2) Sensor #2 Input goes from low to high
- 3) Sensor #1 Input goes from low to high (while Sensor #2 Input remains high)
- 4) **STOP** relay will activate and the **HORN** relay will flash.

Note:

If Sensor #2 Input goes high while Sensor Input #1 is high,

then the STOP relay will not turn on.

However, the GO LIGHT relay will turn on prompting the car to exit.



#### 2.2.2 Outputs

All Outputs have an isolation relay.

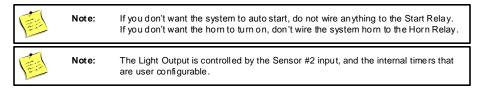
The **Stop** isolation relay is wired Normally Closed.

The **Start** isolation relay is wired Normally Open.

The **Horn** isolation relay is wired Normally Open.

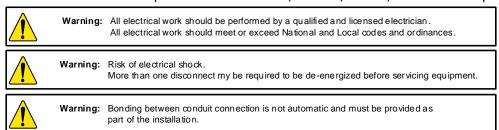
The **Light** isolation relay is wired Normally Open.

Relays can be manually overridden by using the Override latch on the corresponding relay.



#### 2.2.3 Field Wiring

Convenience terminals are provided for **Sensor #1 Input** and **Conveyor Enable**. **Sensor #2 Input** is wired directly to the Loop Detector Relay Socket Base. Convenience terminals are provided for the **STOP**, **START**, **HORN**, and **LIGHT** outputs.



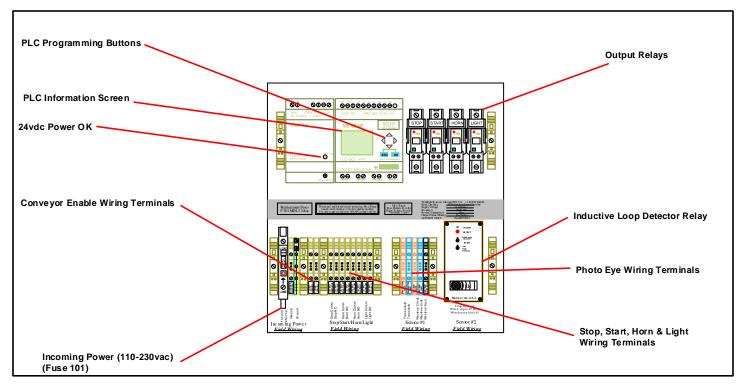


Figure 2.0 Field Wiring

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#### 3 Programming

To get into programming mode, press the button until the time and date screen appears. fig1

When the Time and Date screen appears, press the ESC button and the following screen will appear. fig2



fia1



ia2

#### 3.1 Setting Time & Date

Use the button and scroll to Set Clock and the press the OK button. fig2

Use the



buttons to scroll between fields and adjust the values, then press OK . fig3



fig3

#### 3.2 Programming Go/Exit Light

The Go/Exit light function operates once each time the sensor #2 goes high There are two settings;

On Delay, amount of time before turning on after sensor #2 goes high Off Delay, amount of time to stay on after the On Delay has expired.

While in Programming Mode;

Scroll using the button until you get to set Parm and then press the OK button. fig4

Use the



buttons to scroll between fields and adjust the values, then press OK . fig5

On Delay = TH

(if you want 20 second on delay TH=00:20m)

Off Delay = TL

(if you want 15 second on delay TL=00:15m)

>Stop Set Param Set Clock Prg Name

ig4



tig5



#### 3.3 Programming On Delay for Sensors

These On Delay's will tell the system to not pay attention to the Sensor #1 and Sensor #2 input signals until this amount of time has expired

#### While in Programming Mode;

Scroll using the button until you get to set Parm and then press the OK button. Fig6

Scroll using the button until you get to #1\_Delay or #2\_Delay and then press the OK button. Fig7 & 8

Use the buttons to scroll between fields and adjust the values, then press OK . fig7

On Delay = T

(for 1.5 Seconds, T= 01:50s)



#2\_Delay

Ta=XX:XXs

#2\_Delay
T =XX:XXs

Ta=XX:XXs

ia8

To exit the programming mode, press ESC unitl the time and date message screen appears. Fig9



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#### 4 System status information screens

During normal operation, the following information messages will appear

TOTAL CAR
COUNT XXX
Resets to 0
At 1000000

Car Count based on sensor detections

COLLISION SENSOR ONE ACTIVATED

Sensor #1 input high

COLLISION SENSOR TWO ACTIVATED

Sensor #2 input high

COLLISION SENSORS ONE AND TWO ACTIVATED

Sensor #1 input high And Sensor #2 input high

CONVEYOR STOPPED FOR COLLISION AVOIDANCE

Stop relay activated because of collision avoidance condition

GO LIGHT ACTIVATED

Light relay activated

#### 4.1 Reset total car count to 0

To reset the car counter, momentarily apply 24vdc (P1) to input #8



#### 5

**Wiring Diagram**The following pages are dedicated to the wiring diagram for the Collision Avoidance Controller.

PAGE	DESCRIPTION
5.1	COVER SHEET
5.2	PLC WIRING
5.3	INTERCONNECTS
5.4	PANELLAYOUT
5.5	SENSOR LAYOUT

REV	BY	DATE	DESCRIPTION
1.0.3	MTS	101201	FOR APPROVAL
2.0.3	MTS	110418	TYPOS, CLARIFICATIONS, INTERCONNECTS
2.0.3	MTS	110419	ADDED RESET BUTTON

#### NOTES:

- 1. STANDARD SUPPLY VOLTAGE IS 120/240VAC 60/50Hz.
- 2. TO AVOID RISK OF FIRE AND PERSONAL INJURY, REPLACE ONLY WITH MANUFACTURER'S ORIGINAL RATED FUSE.
- 3. WASHLINK SYSTEMS SUPPLIED JUNCTION BOX.
- 4. EQUIPMENT SUPPLIED BY OTHERS.
- 5. WASHLINK SYSTEMS RECOMMENDS AWG 18 STRANDED COPPER WIRE FOR CIRCUITS LESS THAN 200 FEET.
- 6. WASHLINK SYSTEMS RECOMMENDS AWG 18 STRANDED COPPER 2 CONDUCTOR SHIELDED WIRE FOR CIRCUITS LESS THAN 200 FEET.
- 7. WASHLINK SYSTEMS RECOMMENDS SOLDERING ANY NEEDED JUNCTIONS DO NOT USE WIRE NUTS.
- 8.
- 9. INPUTS ARE 24VDC ONLY. ANY OTHER VOLTAGE WILL DAMAGE CONTROLLER AND VOID MANUFACTURER'S WARRANTY.



ALL ELECTRICAL WORK SHOULD BE PERFORMED BY A QUALIFIED AND LICENSED ELECTRICIAN.
ALL ELECTRICAL WORK SHOULD MEET OR EXCEED NATIONAL AND LOCAL CODES AND ORDINANCES.



CAUTION! RISK OF ELECTRICAL SHOCK. MORE THAN ONE DISCONNECT MY BE REQUIRED TO BE DE-ENERGIZED BEFORE SERVICING THE EQUIPMENT.

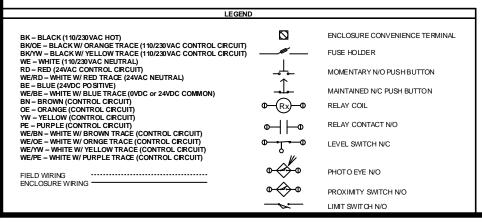


CAUTION! TO REDUCE THE RISK OF FIRE, CONNECT ONLY TO A 110/230VAC CIRCUIT PROVIDED WITH 15A MAXIMUM BRANCH CIRCUIT PROTECTION. IN ACCORDANCE WITH THE NEC, ANSI/NFPA 70 AND LOCAL CODE AUTHORITIES.



CAUTION! BONDING BETWEEN CONDUIT CONNECTION IS NOT AUTOMATIC AND MUST BE PROVIDED AS PART OF THE INSTALLATION.

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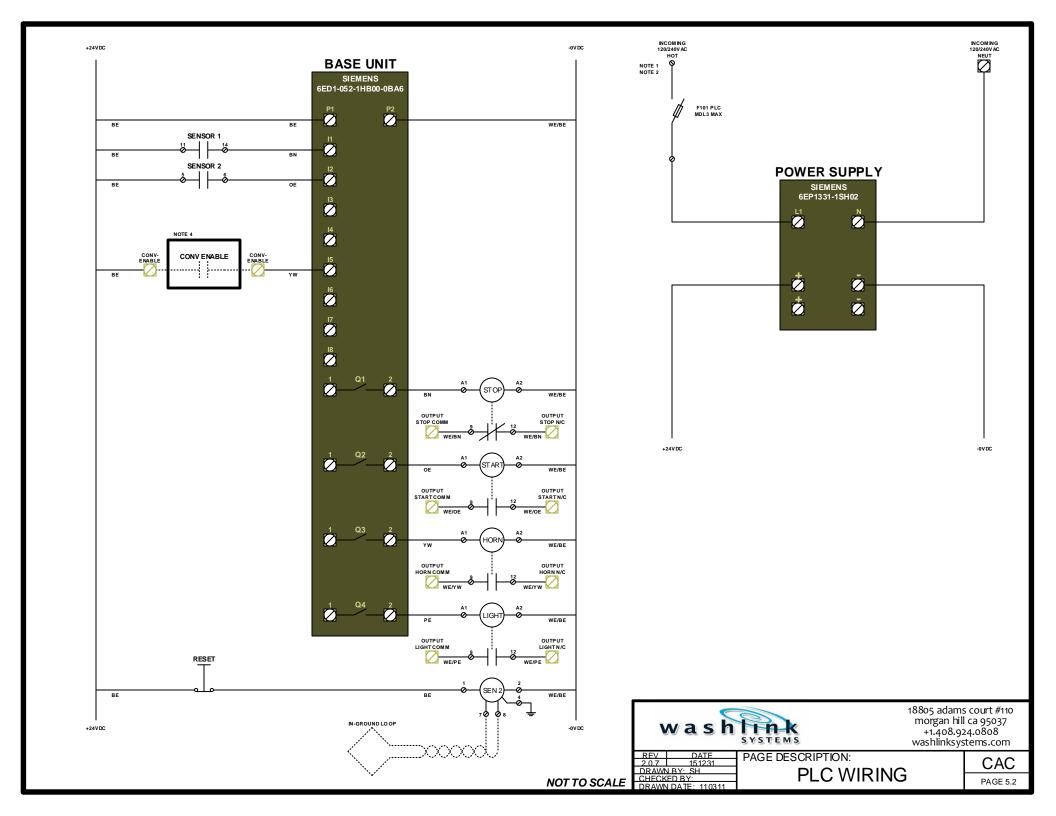
REV DATE 2.0.7 151231 DRAWN BY: SH CHECKED BY: DRAWN DATE: 110311

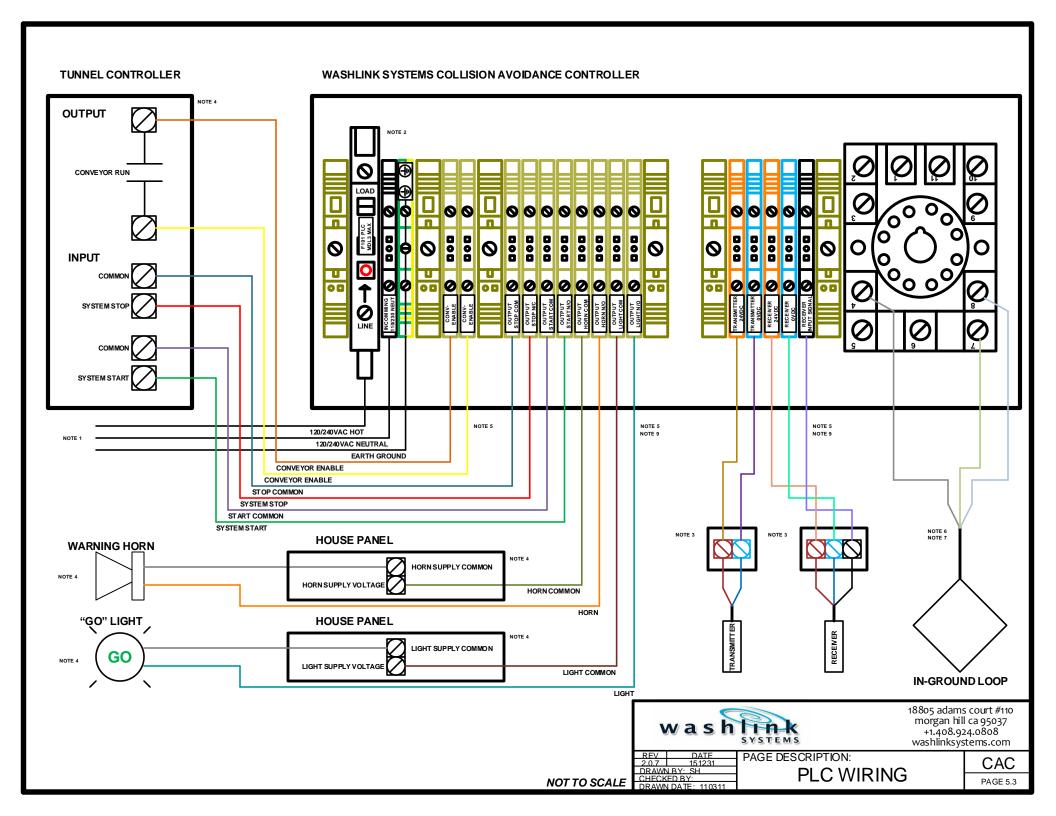
NOT TO SCALE

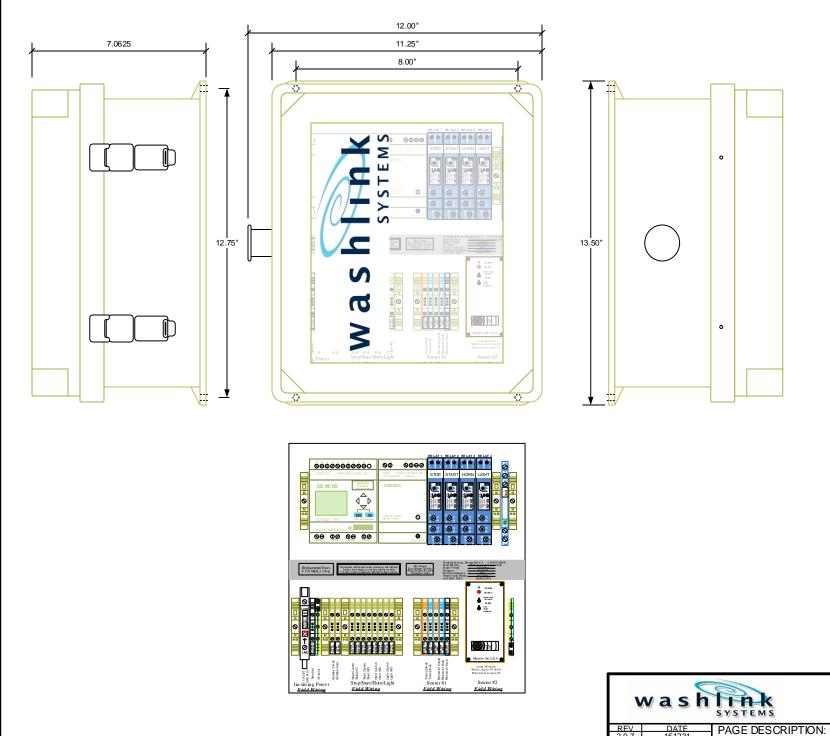
PAGE DESCRIPTION:

COVER SHEET

CAC



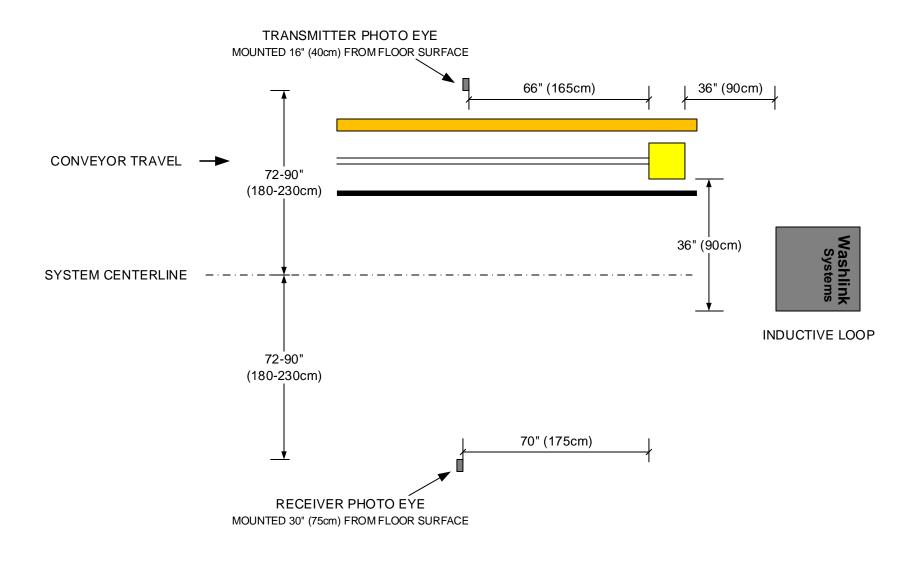




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**LAYOUT** 

CAC PAGE 5.4





CAUTION! DIMENSIONS ARE FOR REFERENCE PURPOSES ONLY. INCREASE THE DISTANCE BETWEEN CARS BEFORE STOPPAGE BY INCREASING THE DISTANCE BETWEEN THE SENSOR LOCATIONS. DECREASE THE DISTANCE BETWEEN CARS BEFORE STOPPAGE BY DECREASING THE DISTANCE BETWEEN THE SENSOR LOCATIONS.



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PAGE DESCRIPTION: SENSOR LAYOUT

CAC PAGE 5.5

**NOT TO SCALE**